

RH-P600AJQ

Programmable Wheeled Encoder

DESCRIPTION

The RH-P encoder, also known as a Pulse Position Indicator (PPI) or Tach, is typically used to measure linear movement on a conveyor system. The number of counts per revolution is determined by setting configuration switches. An optional pair of 12" or 30cm circumference measuring wheels allow it to ride directly on the conveyor belt, tracking the conveyor independently of conveyor roller diameters. The RH-P also includes the Anti-jitter feature that eliminates extraneous counts generated if the conveyor stops on a square wave boundary.

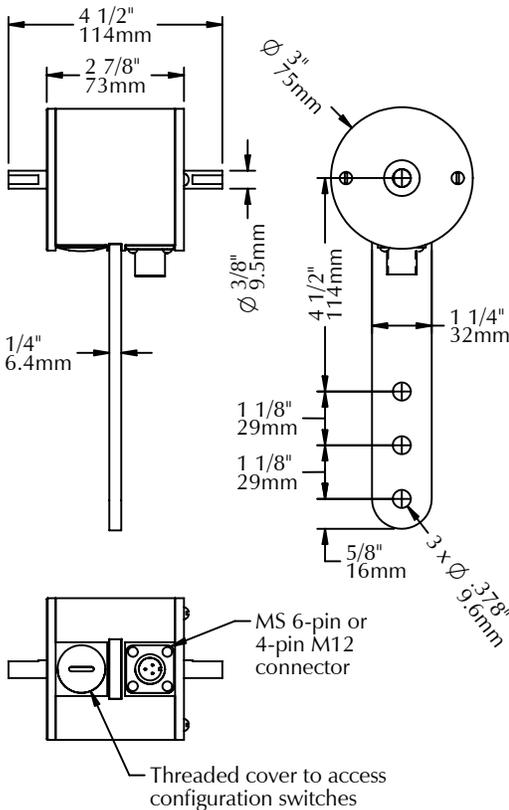
FEATURES

- Programmable Counts per Revolution
- Selectable Output Type:
 - Quadrature A and B outputs
 - Dual Anti-jitter outputs
 - Dual high resolution outputs with Anti-jitter
- ESD / Short Circuit / Reverse Voltage Protected
- See the model R22 for a smaller wheeled encoder

* CE marking requires Photocraft cable, and surge protection option if cable exceeds 100' (30m) or leaves the building.



DIMENSIONS



SPECIFICATIONS

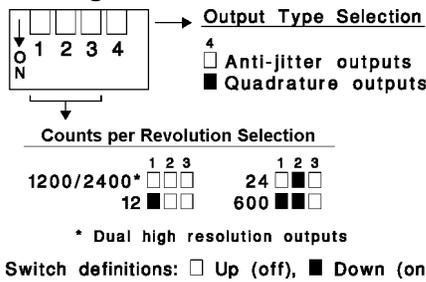
Mechanical

- Weight:** 1.3 lbs (600 gm)
- Shaft Loading:** Radial: 25 lb. (11.3 kg.) max
Axial: 10 lbs. (6.8 kg.) max
- Bearing Life:** 70 x 1,000,000/rpm = hours
- Materials:**
 - Case: Aluminum, anodized
 - Shaft: 303 Stainless steel
 - Switch cover: Plastic
- Maximum Operating Speed:** 1,200 rpm

Electrical

- Supply Voltages (+vdc):** (specify when ordering)
5 ± 5% vdc or 8 to 30 vdc
- Current:** 50 ma max (no load)
100 ma max (line driver)
- Operating Temperature:** 0° to +70° C
- Output Circuit:** (specify when ordering)
Output voltage level is approximately the same as the input voltage level.
- Single Ended:**
 - NPN open collector (30vdc/50mA max)
 - Push/Pull (50mA max source/sink)
- Differential Line Driver:**
 - 7272 line driver (output same as input volts)
 - RS422 line driver (regulated 5vdc output)

Configuration Switches



Outputs

- Anti-jitter Outputs:** Outputs A and B have identical counts per revolution. Output hysteresis is increased to 1/2 of a pulse width (15° for 12 pulses per revolution), eliminating the effects of mechanical vibration and the possible dither that results in false outputs.
- Quadrature Outputs:** Two outputs, A and B, have the selected number of counts per revolution. A leads B by 90° for clockwise rotation when viewed from shaft end farthest from connector.
- Dual High Resolution Outputs:** Output A generates 1200 square wave counts per revolution. Output B generates 2400 fixed size counts per revolution: the output is normally high and goes low for 5microseconds for each count. Hysteresis is increased to 21% of a revolution. That is, the encoder generates counts as long as it rotates in one direction. If the direction reverses then output ceases until the encoder returns to its original direction of rotation and to its position before reversing. If reverse direction exceeds 21% then the encoder resets itself.

Electrical Connections

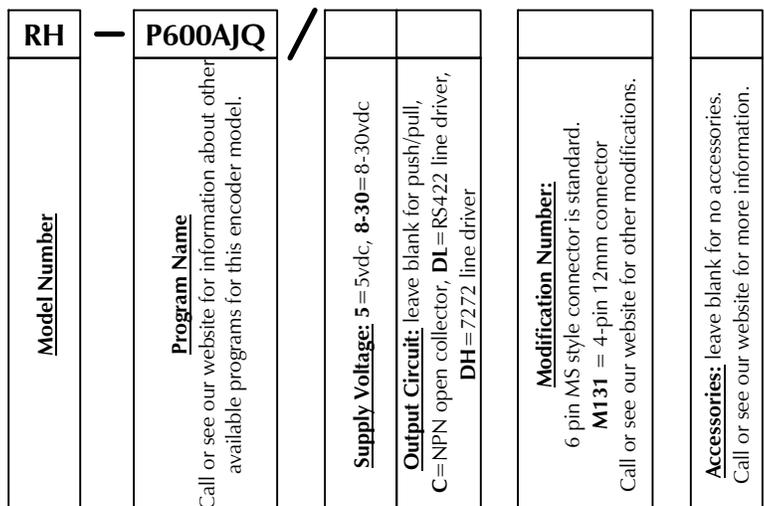
Single Ended Outputs:

MS 6-pin Pin No.	4-pin M12 Pin No.	Function	Wire Color
A	3	Common	Black
B	1	+vdc	Red
D	4	Output A	White
E	2	Output B	Green
C, F	-	not used	-

Differential Line Driver Outputs:

MS 6-pin Pin No.	Function	Wire Color
A	Common	Black
B	+vdc	Red
C	Output +A	White
D	Output -A	Blue
E	Output +B	Green
F	Output -B	Brown

MODEL NUMBER



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Example: RH-P600AJQ/8-30 - model RH, P600AJQ program, 8-30vdc, push/pull output, 6-pin MS style connector